Outline

1. Introduction of the DESIS Team
2. Brief Overview of MUSES and DESIS
3. TCloud Overview and Demonstration
4. Review of Delivered Data
5. Introduction to Data Processing
DESIS Team

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Operations Manager
Acquisition Coordinator
MUSES and DESIS
Overview
Multi-User System for Earth Sensing (MUSES)

► Precision pointing platform, designed in cooperation with NASA, for low-cost earth observation from the International Space Station (ISS).

► Comprised of Platform (ISS external) and Server (ISS internal)

► Up to 4 robotically installed instruments.
  • Payload can be removed and returned to earth for analysis or reuse.

► Total data downlink ~225 GB/day.
  • Onboard processing option.

► < 12 Months: Contract to Launch.
  • ~ 1/3 the cost of a free-flyer mission.

Characteristic | MUSES Performance Target
--- | ---
Field of Regard | Outboard Cross-Track: 5°
               | Inboard Cross-Track: 45°
               | Along-Track: +/- 25°
Thermal Control | Passive
Star Tracker | Sodern SED26
Inertial Measurement Unit | Honeywell Miniature Inertial Measurement Unit (MIMU)
Precision Time | Sourced from the ISS GPS, ≤ ± 250 μsec to MUSES instruments
Pointing Accuracy | ≤ ± 60 arc seconds
Pointing Knowledge | ≤ ± 30 arc seconds (~ 60 m on ground from 400 km altitude)
Location knowledge | Sourced from the ISS GPS, ± 50 meters, RMS
Orbit | 51.6° Inclination, 400 km altitude ± 5% (nominal)
Data Processing | Linux Server on-board ISS with redundant 6 TB storage
Daily Downlink Capacity | 225 GB
Earth Observation From the ISS – Why It Works/Challenges

Benefits
- Coverage of ~90% of populated Earth.
- Coverage of tropics, frequent revisit times off-noon allow for reduced-cloud image acquisition.
- Orbit enables acquisitions at different times of day, useful for BRDF or diurnal dynamics.
- Upgrade, repair and exchange of instruments as technology and/or markets evolution.
- Traditional barriers to entry are minimized.

Challenges
- Above 55° N and below 52° S not covered in orbit.
- Revisit time has a beat frequency that depends on latitude.
Cooperative effort between the German Aerospace Center (DLR) and Teledyne Brown Engineering (TBE)

- MUSES first payload – Launched June of 2018.
- Teledyne has commercial rights to imagery while DLR retains the rights for scientific use.

DLR Earth Sensing Imaging Spectrometer (DESIS)

- 235 bands with 2.55 nm sampling over the VNIR spectral region (400-1000 nm).
- 30 m GSD @ ISS 400 km orbit.
- Sensor pointing ±15° along track, enables BRDF and stereo acquisitions.
- Push Broom Sensor: Maximum length of a single strip ~ 3000 km.
- Each strip is broken into 1024 x 1024 pixel tiles, or 30 x 30 km.
# DESIS Specifications

<table>
<thead>
<tr>
<th>Parameter</th>
<th>DESIS Specification (Commissioning Phase)</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Orbit</strong></td>
<td>not Sun-synchronous, 51.6°, 400 ± 5 km, 93 min, no repeat cycle</td>
</tr>
<tr>
<td><strong>Coverage</strong></td>
<td>55° N to 52° S</td>
</tr>
<tr>
<td><strong>Tilt (across-track, along-track)</strong></td>
<td>+45° to -5°, -40° to +40° by MUSES and DESIS</td>
</tr>
<tr>
<td><strong>Sensor Pointing</strong></td>
<td>±15° along-track to enable BRDF or Stereo acquisitions</td>
</tr>
<tr>
<td><strong>Spectral coverage</strong></td>
<td>402 nm to 1000 nm (Part of FPA defective at low wavelengths)</td>
</tr>
<tr>
<td><strong>Number of spectral channels</strong></td>
<td>235 (no binning); 118 (binning 2); 79 (binning 3); 60 (binning 4)</td>
</tr>
<tr>
<td><strong>Spectral Sampling resolution</strong></td>
<td>2.55 nm (w/o binning); ~10.2 nm (binning 4)</td>
</tr>
<tr>
<td><strong>Full Width Half Maximum (FWHM)</strong></td>
<td>~3.5 nm (w/o binning); ~10.5 nm (binning 4)</td>
</tr>
<tr>
<td><strong>Radiometric resolution</strong></td>
<td>12 bits + 1 bit gain</td>
</tr>
<tr>
<td><strong>Radiometric Accuracy</strong></td>
<td>±10% (based on on-ground calibration and with support of inflight radiometric calibration; Expect ±5%)</td>
</tr>
<tr>
<td><strong>Radiometric Linearity</strong></td>
<td>99%</td>
</tr>
<tr>
<td><strong>Swath</strong></td>
<td>30 km</td>
</tr>
<tr>
<td><strong>Spatial resolution, pixels</strong></td>
<td>30 m, 1024 pixels (@400 km)</td>
</tr>
<tr>
<td><strong>Geometric accuracy</strong></td>
<td>~20 m with GCPs</td>
</tr>
<tr>
<td></td>
<td>~300 m - 400 m w/o GCPs (i.e. water only collects)</td>
</tr>
<tr>
<td><strong>MTF @ Nyquist</strong></td>
<td>30%-40% based on on-ground calibration / static MTF without smearing effects / wavelength depending</td>
</tr>
<tr>
<td><strong>Signal-to-Noise ratio (albedo 0.3 @ 550 nm)</strong></td>
<td>195 (w/o binning)</td>
</tr>
<tr>
<td></td>
<td>386 (4 binning)</td>
</tr>
<tr>
<td><strong>Solar zenith angle restrictions</strong></td>
<td>&gt; 55° produces reduced quality L2A product</td>
</tr>
<tr>
<td>(for L2A level processing)</td>
<td>&gt; 65° produces low quality L2A product</td>
</tr>
<tr>
<td></td>
<td>&gt; 70° not processible to L2A</td>
</tr>
</tbody>
</table>
TCloud
Overview and Demonstration
TCloud Overview

► TCloud is a Teledyne Brown Engineering – Geospatial Solutions cloud-based data management and distribution system for geospatial imagery.
  • Front end – user interface
  • Back end – data processing

► Allows approved users to submit DESIS sensor tasking requests and/or order archived DESIS data and retrieve the requested data.

► Allows for post-processing of the data in multiple ways.
TCloud Demonstration

TCloud Website: https:\teledyne.tcloudhost.com
DESIS
Data Delivery
## Product Overview

- **DESIS L1A raw data stored in archive**
  - Not an available product

- **Several levels of processing available for end-users**
  - L1B Radiance
  - L1C Orthorectified Radiance
  - L2A Surface Reflectance *(Coming Soon)*

- **Processing applied on-the-fly in the online archive when data is ordered**
Order Download

- DESIS data ordered from TCloud is delivered either via user download from the TCloud repository or to an AWS S3 bucket
  - Each requested product/tile is provided as a separate zip file
  - Users are sent an email when ordered data is available for download
  - Users may also download directly from their order history
DESIS Delivered Files

Each delivered zip file contains:
- QuickLook Image
- Metadata File
- Quality Image
- Ancillary Files
- Hyperspectral Image

Expected zip file data volumes:
- Full spectral resolution data
  - 400 – 600 MB
- Binned x 4 (10.2 nm)
  - 100 – 200 MB

File Naming Convention
DESIS-HSI-L<XX>-DT<nnnnnnnnn>_fff<yyyymmd>d_T<hhmmss>-V<vvvv>-<file type>.<ext>
Where, <XX> is the product level (1B, 1C or 2A)
<nnnnnnnnn> is a unique identifier from the planning system
<fff> is the tile number of the image strip
<yyyymmd>d> is the date in year, month, day format
<hhmmss> is the time in UTC (hour, minute, second)
<vvvv> is the image processor version number
<file type> is the type of file (SPECTRAL_IMAGE, QL_QUALITY, QL_IMAGE, or METADATA)
<ext> is the file extension (tif, xml, or hdr)
QuickLook Image

► Each delivered tile includes a QuickLook image tif file (*QL_Image.tif)
  • 3-band (~500 nm, 650 nm and 850nm) 8-bit image

► Viewable using standard and image processing software
  • Windows Photo Viewer
  • ENVI
  • Imagine
  • MATLAB

Lake Erie/Toledo OH, August 28, 2019
L2A Surface Reflectance QuickLook Image
Metadata File

- Metadata includes information about the sensor, acquisition and processing in xml format (*METADATA.xml)
  - Image corner coordinates, acquisition times and sun and sensor geometry at the time of acquisition are provided
  - Center wavelengths, spectral band information, and scale factors (gains and offsets) are provided for each band
  - Information relating to the image orthorectification is also included for L1C and higher products

- Text file viewable using web browser (e.g. Internet Explorer) or text editor (e.g. WordPad or Notepad)

- Metadata fields described in Section 5.1 of DESIS Product Specifications: https://tbe.com/__documents/PDFs/DESIS_Specifications.pdf
Metadata File Contents (1)

- **Metadata file contents**
  - File information
  - Processing parameters (product type, resampling, map projection)
  - Base parameters (location, time, processing level)

Specific Parameters continued on next slide

Bounding Polygon Coordinates

Acquisition Time
Metadata File Contents (2)

► Specific Parameters
  • Sensor information
  • Orbit and processing information
  • Product dependent processing information
  • Acquisition information (sun and sensor geometry)
Metadata File Contents (3)

Band Characteristics provided for each spectral band

- Center wavelength (nm)
- Band FWHM (nm)
- Band spectral response and corresponding wavelengths
- Gain and Offset
  - For conversion to radiance or reflectance
- % dead or suspicious pixels

Code Example:
```
- <band>
  <bandNumber>10</bandNumber>
  <wavelengthCenterOfBand>425.3</wavelengthCenterOfBand>
  <wavelengthWidthOfBand>3.6</wavelengthWidthOfBand>
  <response>1.31e-05, 2.15e-05, 3.498e-05, 5.58e-05, 8.77e-05, 1.36e-04, 2.07e-04, 3.12e-04, 4.62e-04, 6.73e-04, 9.66e-04, 1.36e-03, 1.90e-03, 2.60e-03, 3.51e-03, 4.66e-03, 6.09e-03, 7.83e-03, 9.91e-03, 1.24e-02, 1.52e-02, 1.83e-02, 2.17e-02, 2.54e-02, 2.93e-02, 3.31e-02, 3.69e-02, 4.05e-02, 4.37e-02, 4.64e-02, 4.85e-02, 4.99e-02, 5.05e-02, 5.03e-02, 4.93e-02, 4.75e-02, 4.51e-02, 4.22e-02, 3.87e-02, 3.50e-02, 3.12e-02, 2.73e-02, 2.36e-02, 2.00e-02, 1.67e-02, 1.37e-02, 1.11e-02, 8.83e-03, 6.92e-03, 5.34e-03, 4.05e-03, 3.03e-03, 2.23e-03, 1.61e-03, 1.15e-03, 8.08e-04, 5.58e-04, 3.80e-04, 2.55e-04, 1.68e-04, 1.09e-04, 7.01e-05, 4.42e-05, 2.75e-05, 1.68e-05, 1.02e-05</response>
  <wavelengths>418.80, 419.00, 419.20, 419.40, 419.60, 419.80, 420.00, 420.20, 420.40, 420.60, 420.80, 421.00, 421.20, 421.40, 421.60, 421.80, 422.00, 422.20, 422.40, 422.60, 422.80, 423.00, 423.20, 423.40, 423.60, 423.80, 424.00, 424.20, 424.40, 424.60, 424.80, 425.00, 425.20, 425.40, 425.60, 425.80, 426.00, 426.20, 426.40, 426.60, 426.80, 427.00, 427.20, 427.40, 427.60, 427.80, 428.00, 428.20, 428.40, 428.60, 428.80, 429.00, 429.20, 429.40, 429.60, 429.80, 430.00, 430.20, 430.40, 430.60, 430.80, 431.00, 431.20, 431.40, 431.60, 431.80</wavelengths>
  <gainOfBand>0.0001</gainOfBand>
  <offsetOfBand>0.0</offsetOfBand>
  <deadPixels>0.0</deadPixels>
  <suspiciousPixel>0.0</suspiciousPixel>
- </band>
- <band>
  <bandNumber>11</bandNumber>
```
Quality File

*Quality file provides location of defect or suspect pixels, and identifies the quality issue (*QL_QUALITY.tif)*

- 8-bit tif with same number of bands as hyperspectral image
- Each bit provides a flag for possible image quality issues
  - Pixel with quality issue (and surrounding pixels) have appropriate bit set to 1

<table>
<thead>
<tr>
<th>Bit Value</th>
<th>Quality Flag</th>
</tr>
</thead>
<tbody>
<tr>
<td>7</td>
<td>Not Used</td>
</tr>
<tr>
<td>6</td>
<td>Unreliable Calibration</td>
</tr>
<tr>
<td>5</td>
<td>Manufacturing Defect</td>
</tr>
<tr>
<td>4</td>
<td>No Data</td>
</tr>
<tr>
<td>3</td>
<td>Low Radiance Value</td>
</tr>
<tr>
<td>2</td>
<td>High Radiance Value</td>
</tr>
<tr>
<td>1</td>
<td>Suspicious</td>
</tr>
<tr>
<td>0</td>
<td>Dead</td>
</tr>
</tbody>
</table>
L2A Quality-2 File

L2A surface reflectance products are delivered with an additional quality file in a 10-band 8-bit tif (*QL_QUALITY-2.tif)

- Per pixel classification with 8 mask layers (0=false, 1=true)
- Aerosol optical depth at 550 nm (layer 9, scaled by 100)
- Water vapor in cm (layer 10, scaled by 42)

<table>
<thead>
<tr>
<th>Layer</th>
<th>Pixel Classification</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Shadow</td>
</tr>
<tr>
<td>2</td>
<td>Clear Land</td>
</tr>
<tr>
<td>3</td>
<td>Snow</td>
</tr>
<tr>
<td>4</td>
<td>Haze over land</td>
</tr>
<tr>
<td>5</td>
<td>Haze over water</td>
</tr>
<tr>
<td>6</td>
<td>Cloud over land</td>
</tr>
<tr>
<td>7</td>
<td>Cloud over water</td>
</tr>
<tr>
<td>8</td>
<td>Water</td>
</tr>
</tbody>
</table>
Ancillary Files

- **ENVI format header file (*.hdr)**
  - Includes projection information for rectified image display
  - Includes per band center wavelengths and scale factors required to convert data to radiance or reflectance

- **Product history file (*.HISTORY.xml)**
  - Contains information about the executed processing steps and the algorithms and files used to produce the data product
Hyperspectral Image

- Spectral image file contains the hyperspectral data (*SPECTRAL_IMAGE.tif)
  - 16-bit tif with a separate image layer per hyperspectral band
  - Scaled DN

- Requires image processing software or specialized reader to view
  - ENVI
  - Imagine
  - MATLAB/Python
DESIS
Data Processing Introduction
Image Processing Software

- Specialized software is required to import, visualize and generate products from scientific image data
  - Software enables full exploitation of geometric and spectral properties of remotely sensed data

- Software specifically designed for image processing
  - ENVI (L3 Harris) developed for hyperspectral imagery analysis
  - ERDAS Imagine

- Programming software with significant image processing capability
  - MATLAB (MathWorks)
  - Python (open source)

Examples will be shown using hyperspectral imagery in ENVI
Image Visualization

- ENVI can be used to view the image
  - Band selection for RGB display

- Spectral profiles can also be viewed
  - Included .hdr file automatically read and used to define wavelengths
Georeferencing information included in the .hdr is also automatically applied by the image processing software.

- Orthorectified products (L1C and L2A) only.
Converting to Radiance/Reflectance

► Hyperspectral imagery provided in int16 scaled DN format
  • Gains and offsets provided in the .xml metadata for each spectral band convert the data to radiance (L1B, L1C) or reflectance (L2A)
    - Radiance units mW cm⁻² sr⁻¹ μm⁻¹

► The .hdr file included with each DESIS image also contains the gains and offsets and can be used to convert the data in ENVI
  • Use the Apply Gains and Offsets function in the Toolboxes

$$L_{i,j,B} = G_B \times DN_{i,j,B} + O_B$$

Where, $L_{i,j,B}$ = Radiance (or reflectance) for pixel $i,j$ per band, $B$
$G_B$ = Gain per band, $B$
$DN_{i,j,B}$ = DN for pixel $i,j$ per band, $B$
$O_B$ = Offset per band, $B$
Radiance/Reflectance Conversion in ENVI

- Apply Gain and Offset Tool in the Radiometric Correction Toolbox
  - Converts L2A to reflectance
  - Converts L1B, L1C to radiance
    - Can apply different atmospheric correction algorithm

- Floating point output radiance/reflectance
Radiance/Reflectance Conversion Output
Simple Product Generation

- ENVI toolbox has pre-built products and application (spectral indices, classification, feature extraction)
  - Convert data to radiance or reflectance
  - Apply desired tool
Resources

- TCloud may be accessed at [https://teledyne.tcloudhost.com](https://teledyne.tcloudhost.com)
- Additional information about DESIS imagery, files and processing algorithms can be found at [https://tbe.com/geospatial/desis](https://tbe.com/geospatial/desis)
- Contacts information
  - TCloud access: Yvonne Ivey at Yvonne.Ivey@nasa.gov
  - TCloud operation or data ordering questions: Heath Lester at Heath.Lester@Teledyne.com
  - DESIS technical or calibration questions: Kara Burch at kburch@i2rcorp.com
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